



**Pavement**

# **Automated Pavement Inspection**

Vision Technology for Inspection of Transportation Infrastructures

# **and Laser FOD Detection System**

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# **Pavemetrics; Industrial Vision Specialists**



**Pavemetrics Headquarters**  
(Banque Nationale Bldg., QC)

- **Founded 2009; a “Spin-off” of Canada’s National Optics Institute (INO)**
- **Develop high-speed, mm-level scanning and pattern analysis systems**
- **21,000,000+ Miles of Data Collected Since 1997**
- **200 Systems in 30+ countries**

**Pavemetrics**

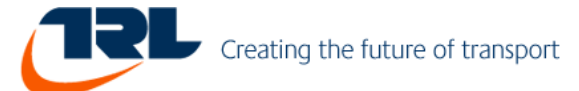
# Solutions for Roads, Runways, Tunnels and Rail



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**Pavemetrics**

# 40+ Global Integrators and Users in 30+ Countries



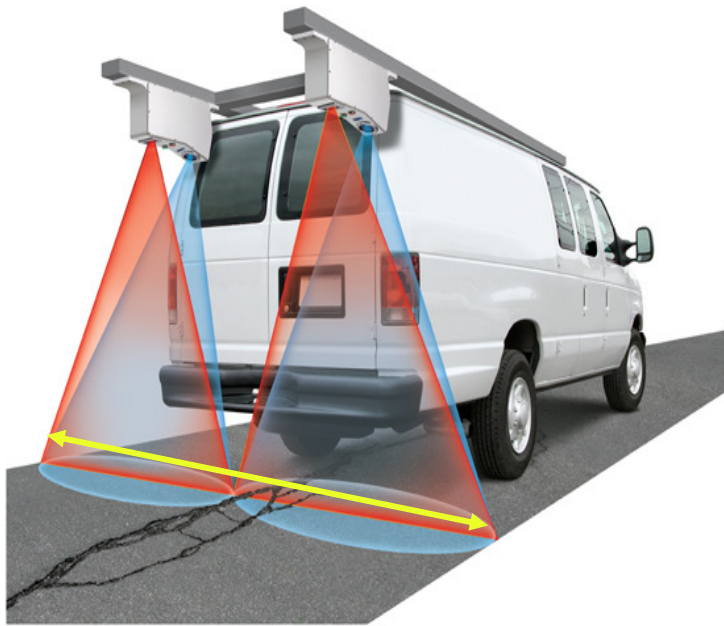
THE UNIVERSITY OF ALABAMA



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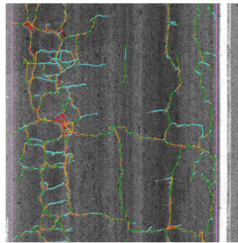


# **LCMS/LFOD Technology**



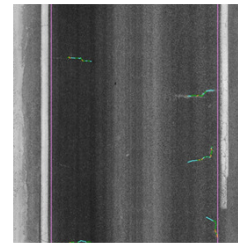
- **2 sensor array that mounts on a vehicle; can be operated at 100km/h**
- **Adjustable 4-6m width per set, can scale up to 18m width**
- **Captures a 3D profile and digital image of the road/runway/rail/tunnel/etc.**
- **Day or night-time operation**
- **Bundled with pattern recognition software to detect features/defects**

# Any Paved Surface

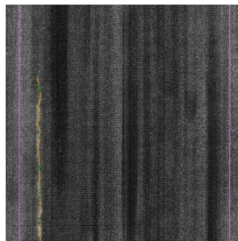


Hotmix

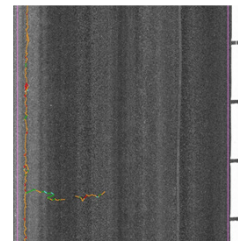
Chipseal



Concrete

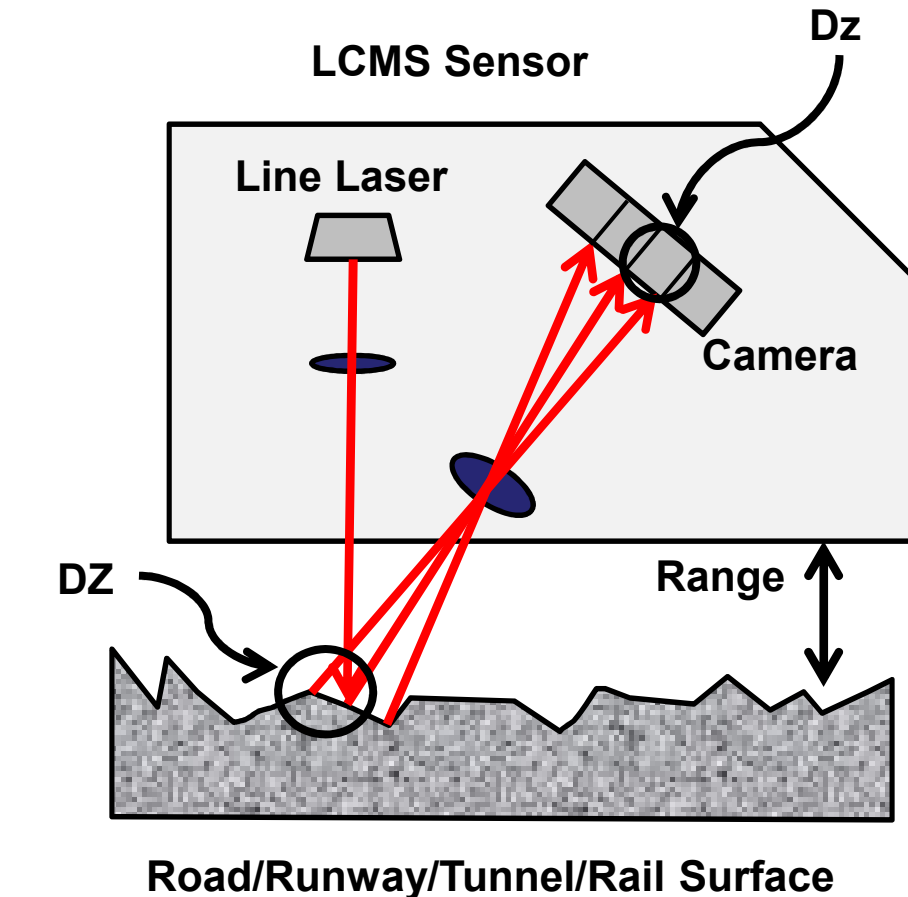


Porous

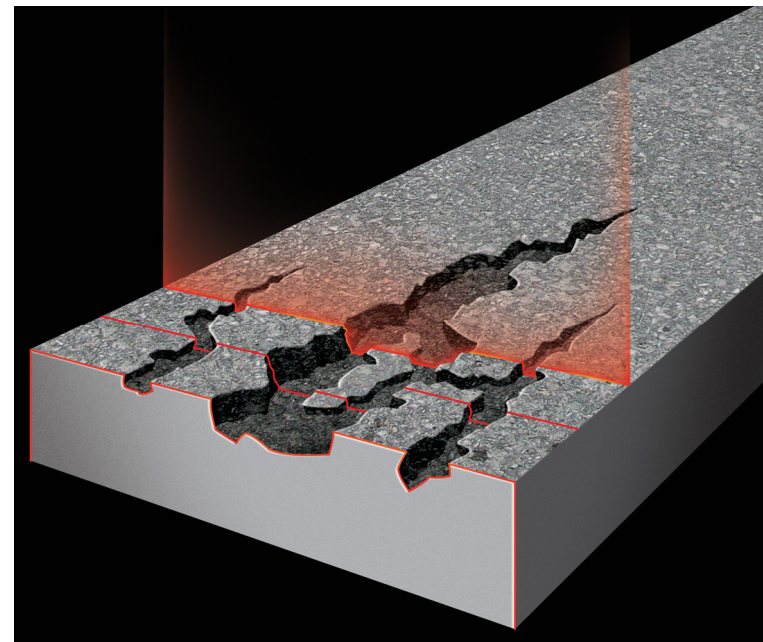


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# Principle of Operation



Road/Runway/Tunnel/Rail Surface  
 $Dz = k * Dz;$



Where **k** is a factor for: distance between surface and lens, focal length of lens, refractive index of lens, distance between lens and sensor, etc...

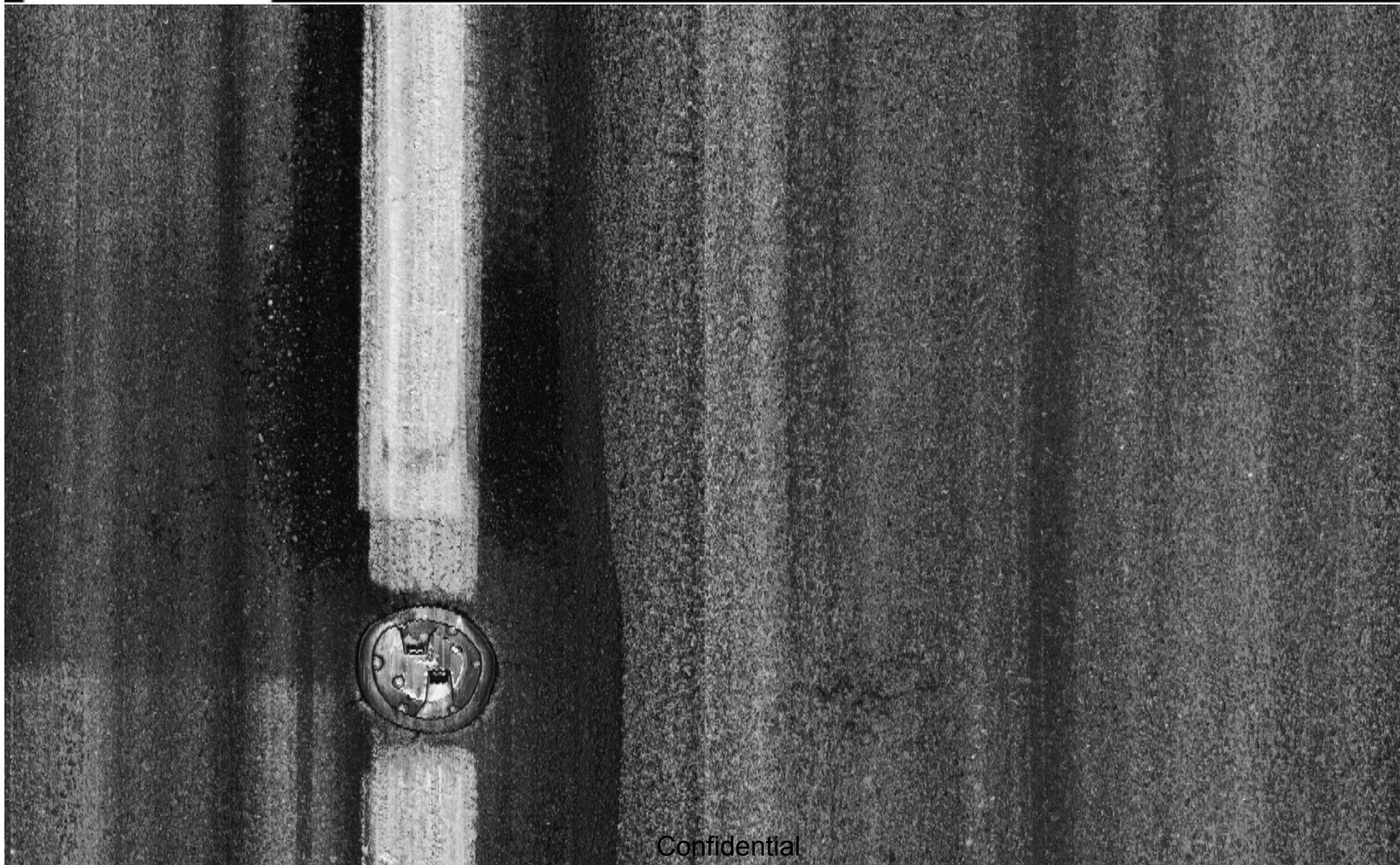
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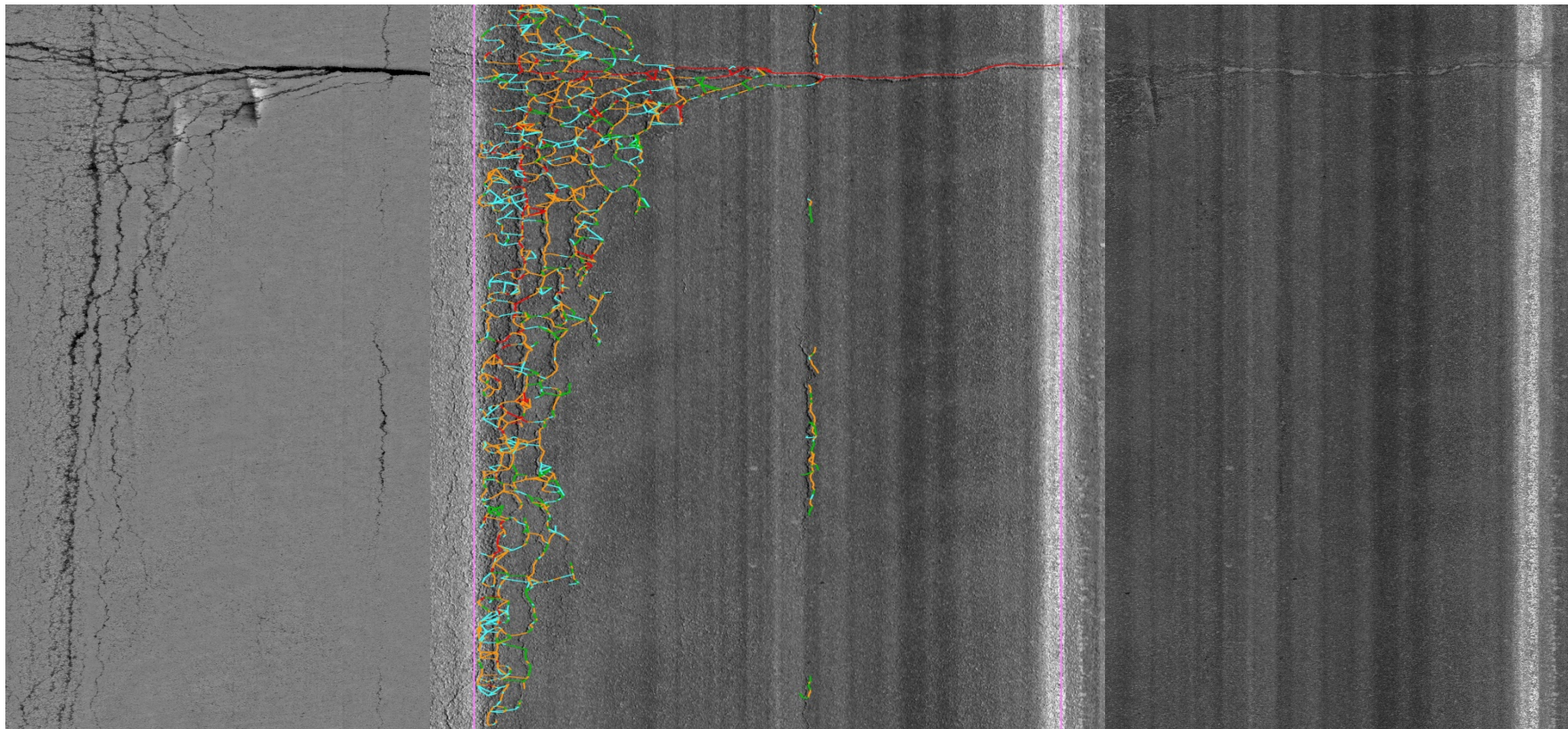
# **Airport Runway Imaging**



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# Understanding 3D Imaging



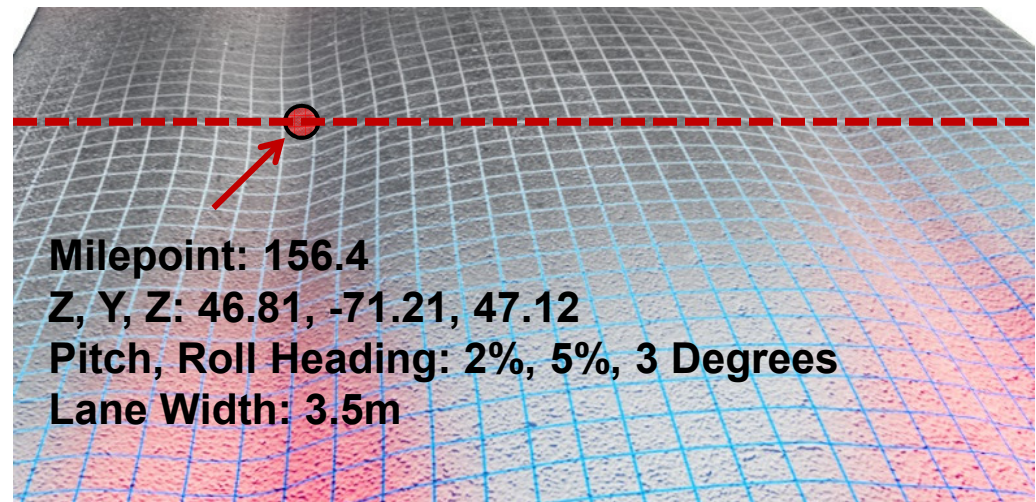
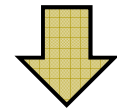
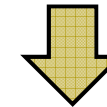
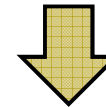
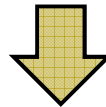
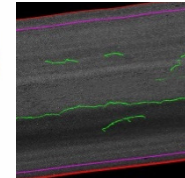
**Range**

**3D**

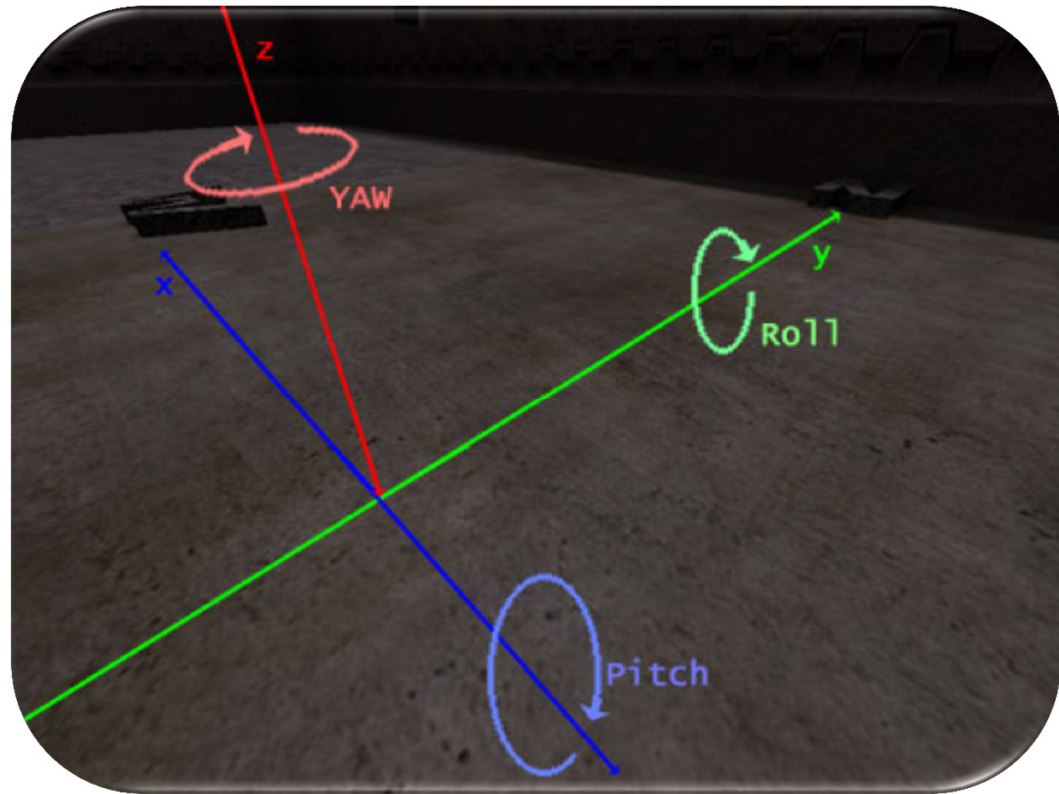
**Intensity**

# Location Referencing and Geometry

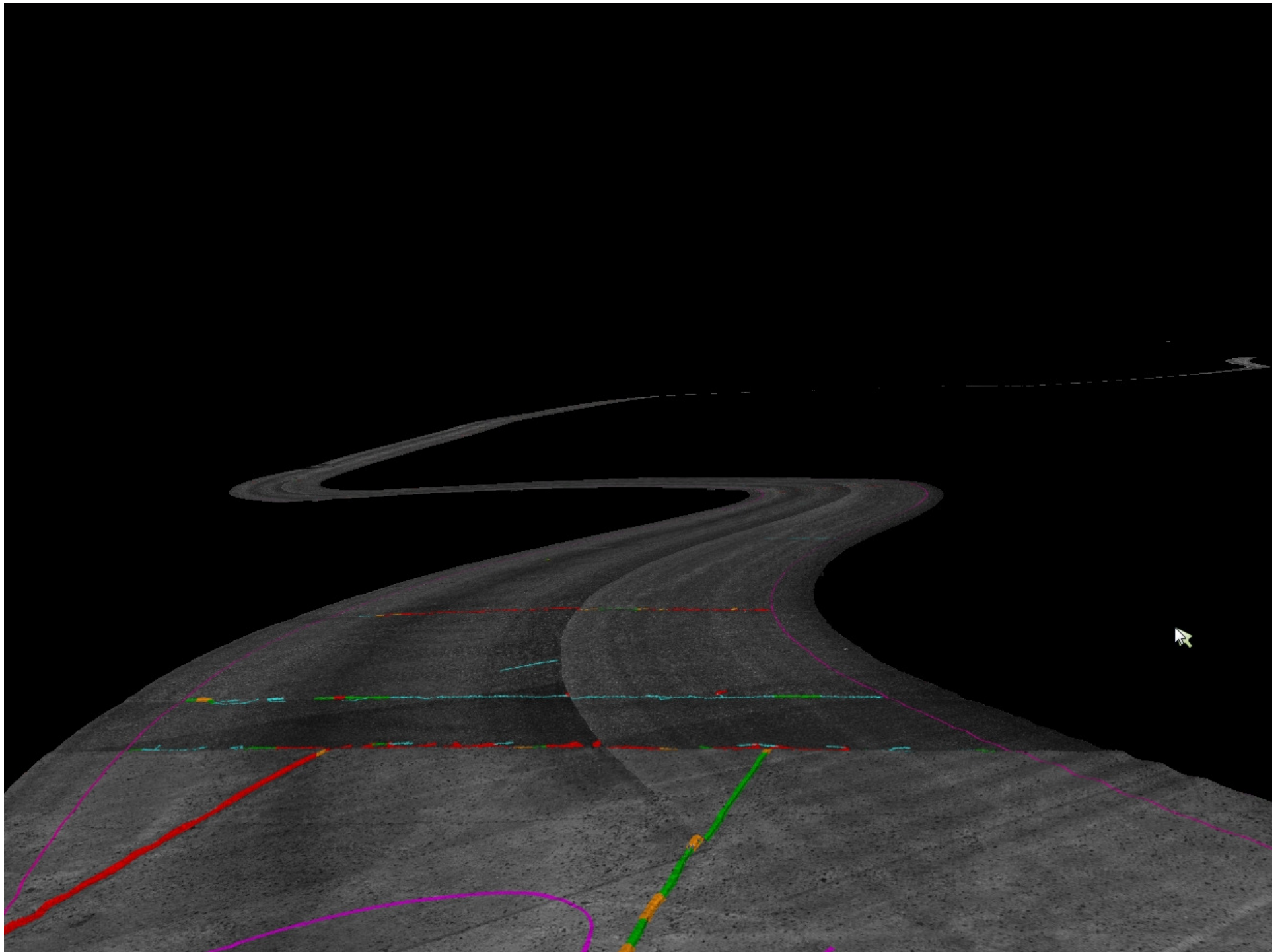
- Optical encoder (DMI) used to measure linear distance
- GPS tagging of each file
- Stripe & edge detection algorithm
- IMU data



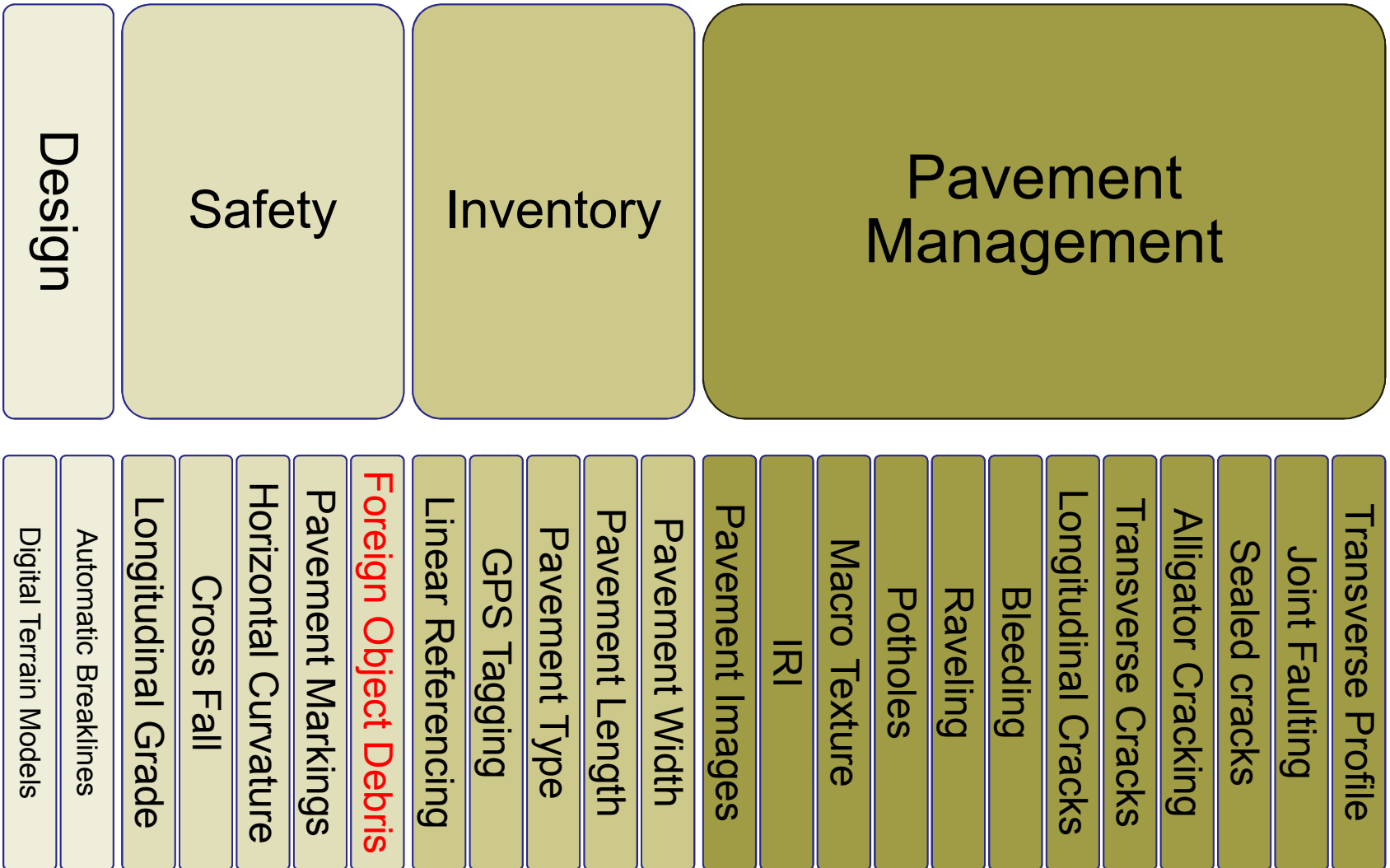








# One Sensor; Many Outputs



# **Data Processing**

# Jointed Concrete Pavement (PCC) – PCI Evaluation

Distress Type	Visual inspection with LCMS viewer	Automatic Detection	Automatic classification
<u>Crack</u>	√	√	√
<u>Faulting</u>	√	√	√
<u>Corner Break</u>	√	√	√
<u>Spalling (joint)</u>	√	√	√
<u>Spalling (corner)</u>	√	√	√
<u>Joint Seal Damage</u>	√	√	√
<u>Popouts</u>	√	√	√
<u>Blowup</u>	√	√	
<u>Durability (D) Crack</u>	√	√	
<u>Scaling</u>	√	√	
<u>Shattered Slab</u>	√	√	
<u>Alkali Silica Reaction</u>	√	√	
<u>Shrinkage Cracking</u>	√		
<u>Patching (small and large)</u>	√		
<u>Pumping</u>			

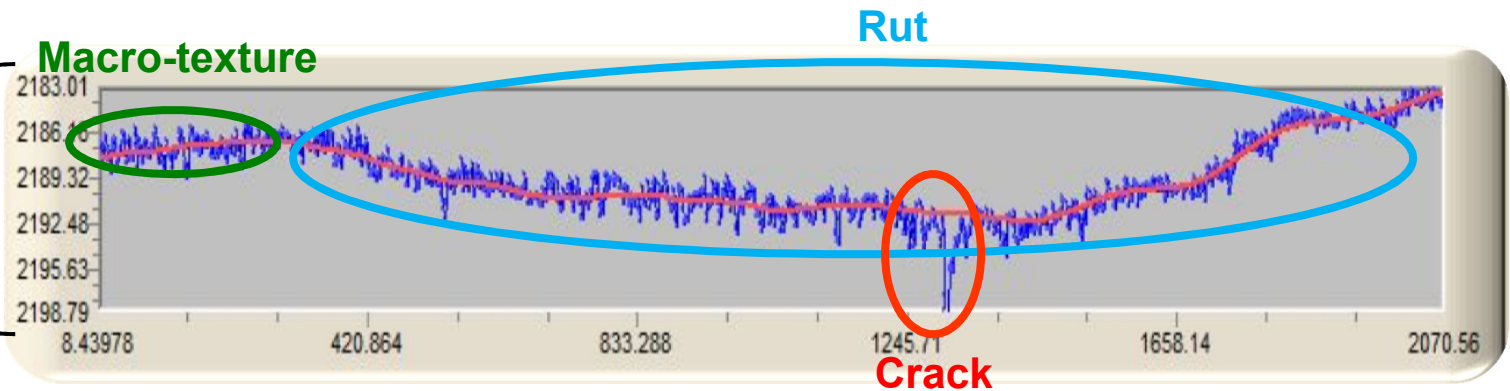


# Asphalt Concrete (AC) – PCI Evaluation

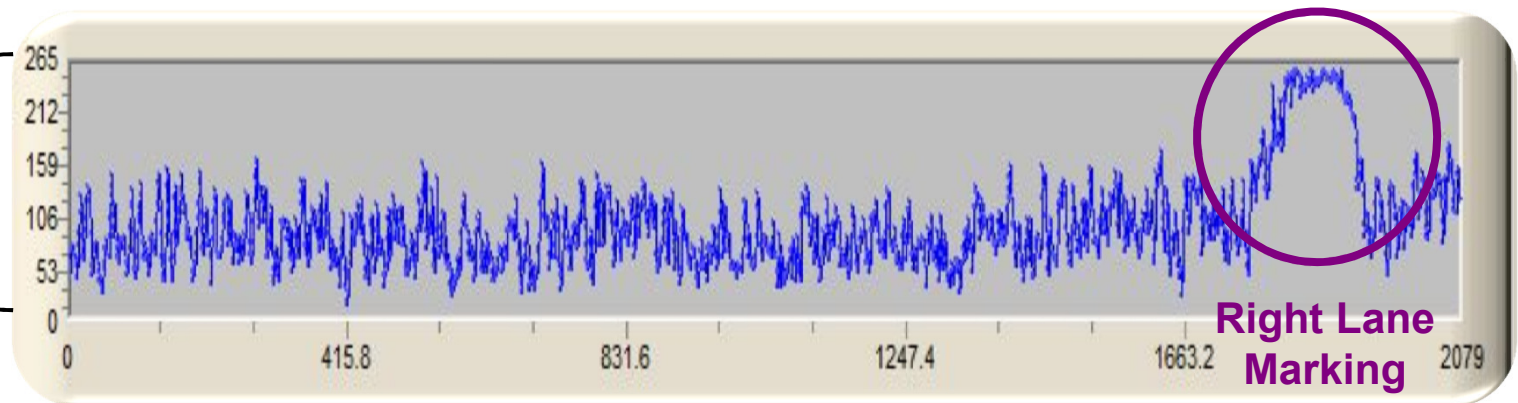
Distress Type	Visual inspection with LFOD viewer	Automatic Detection	Automatic classification
Alligator (Fatigue) cracking	√	√	√
Longitudinal/Transv. cracking	√	√	√
Raveling/Weathering	√	√	√
Rutting	√	√	√
Shoving from PCC	√	√	√
Bleeding	√	√	√
Depression	√	√	√
Block cracking	√	√	
Joint reflection cracking from PCC	√	√	
Slippage cracking	√	√	
Swell-distress	√	√ (if cracks)	
Corrugation	√		
Patching	√		
Jet-Blast Erosion			
Oil-spillage			
Polished aggregate	Confidential		

# Image and Data Analysis

**RANGE**  
Distance  
between  
Sensor and  
ground  
(in mm)



**INTENSITY**  
Laser  
intensity  
(black = 0,  
white = 255)





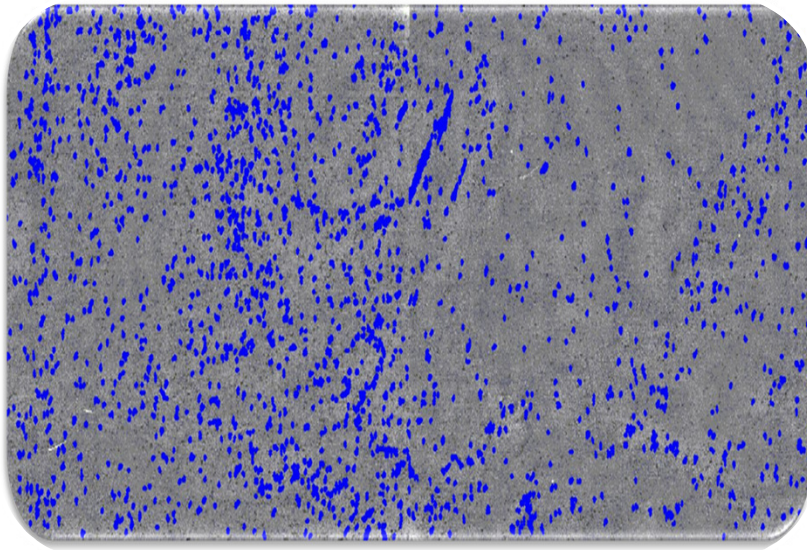
# Crack Detection



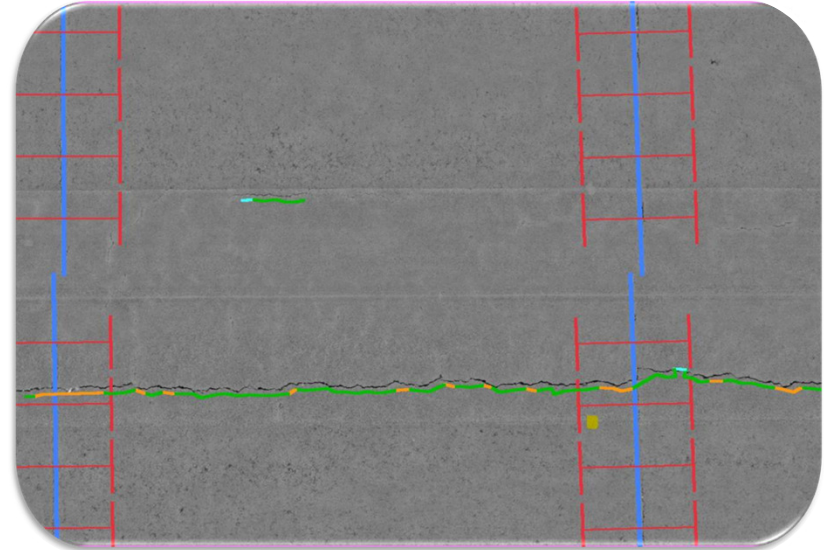
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# **Pavement Assessment Algorithms**



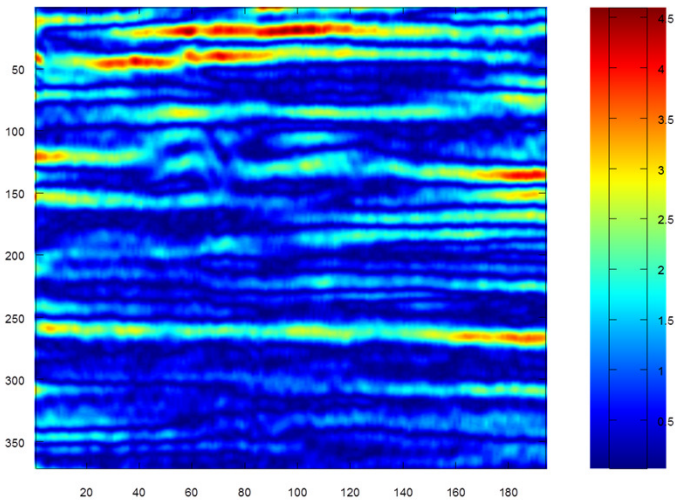
**Raveling  
Detection and  
Quantification**



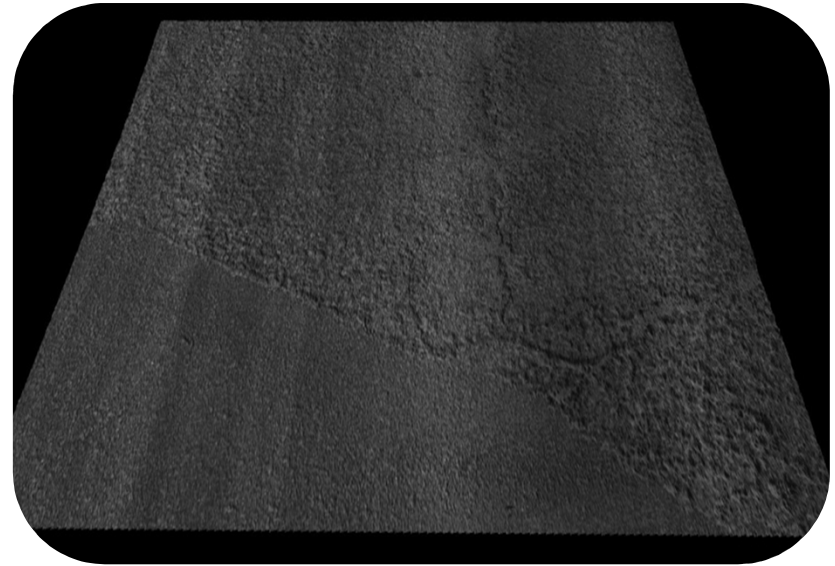
**Joint Detection  
and Measurement**



# Pavement Assessment Algorithms



## Roughness Mapping

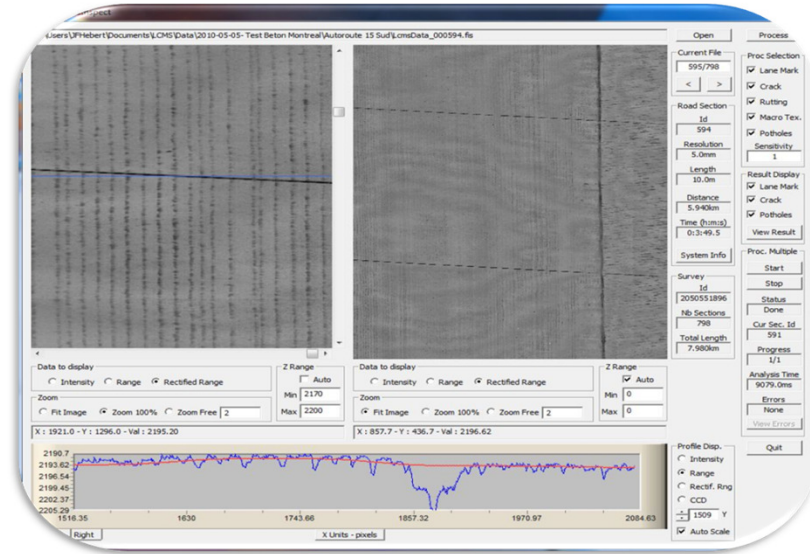


## Macrotexture Measurement

# Pavement Assessment Algorithms



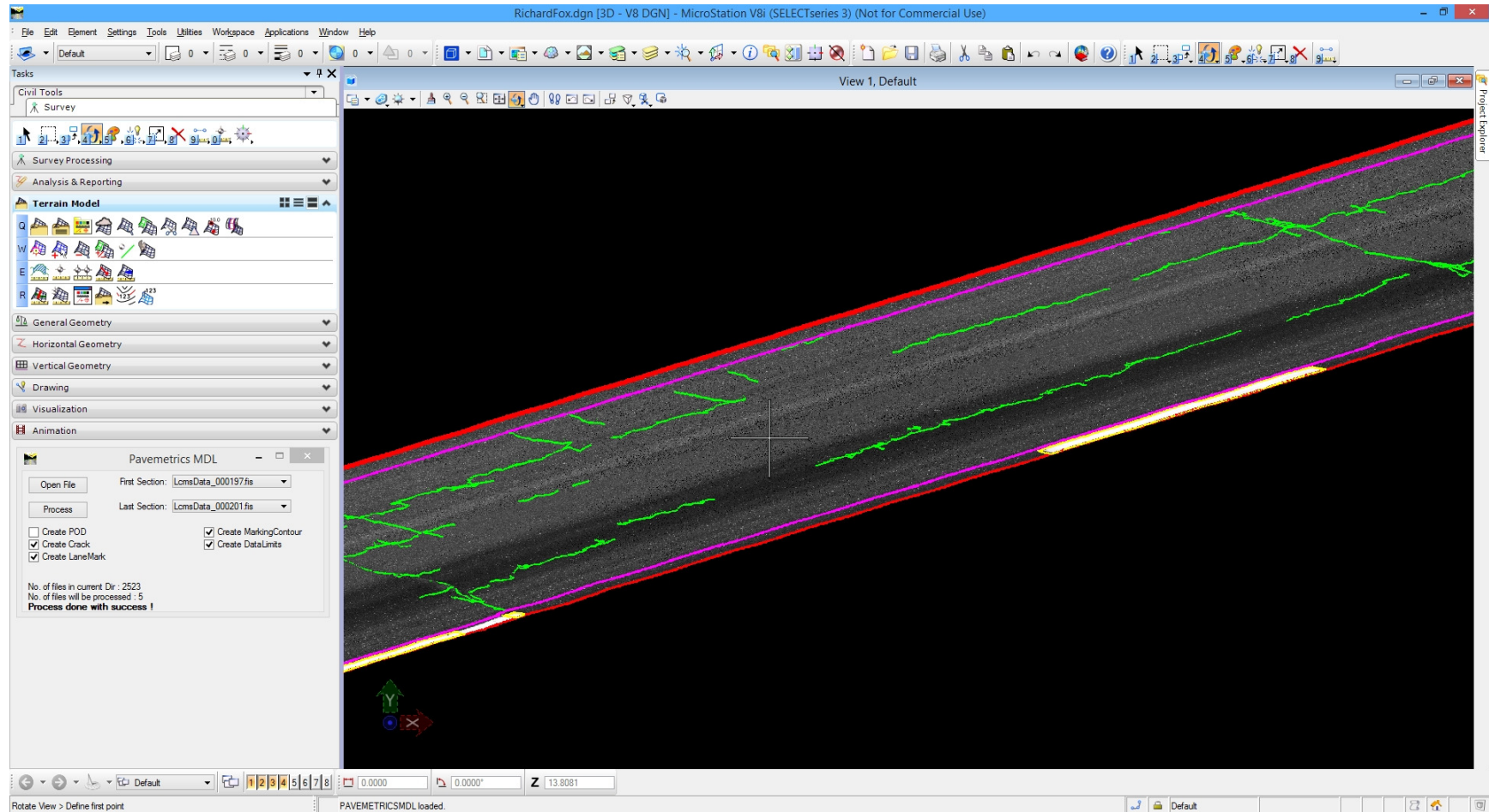
## Bleeding Detection



## Grooving Measurement

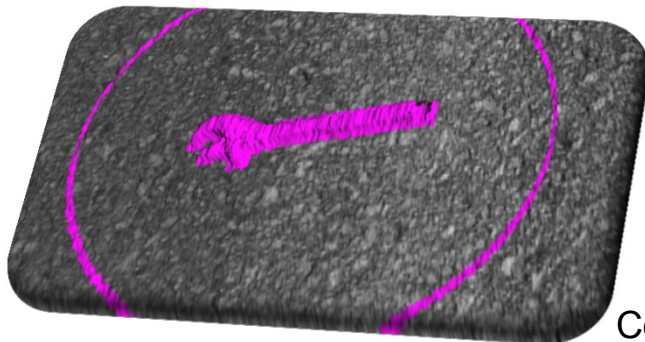
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# Automatic Generation of DTM Data for Bentley





# FOD Detection Algorithm



- Algorithm creates a “virtual plane” and detects any 3D shapes which extend above the plane
- Operates in real-time while vehicle drives at 65 mph
- Algorithm reports FOD height, volume, GPS coordinates and an image
- Operational tool to detect FOD as well as a planning tool to help identify FOD “hot-spots”

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# Photo of FOD

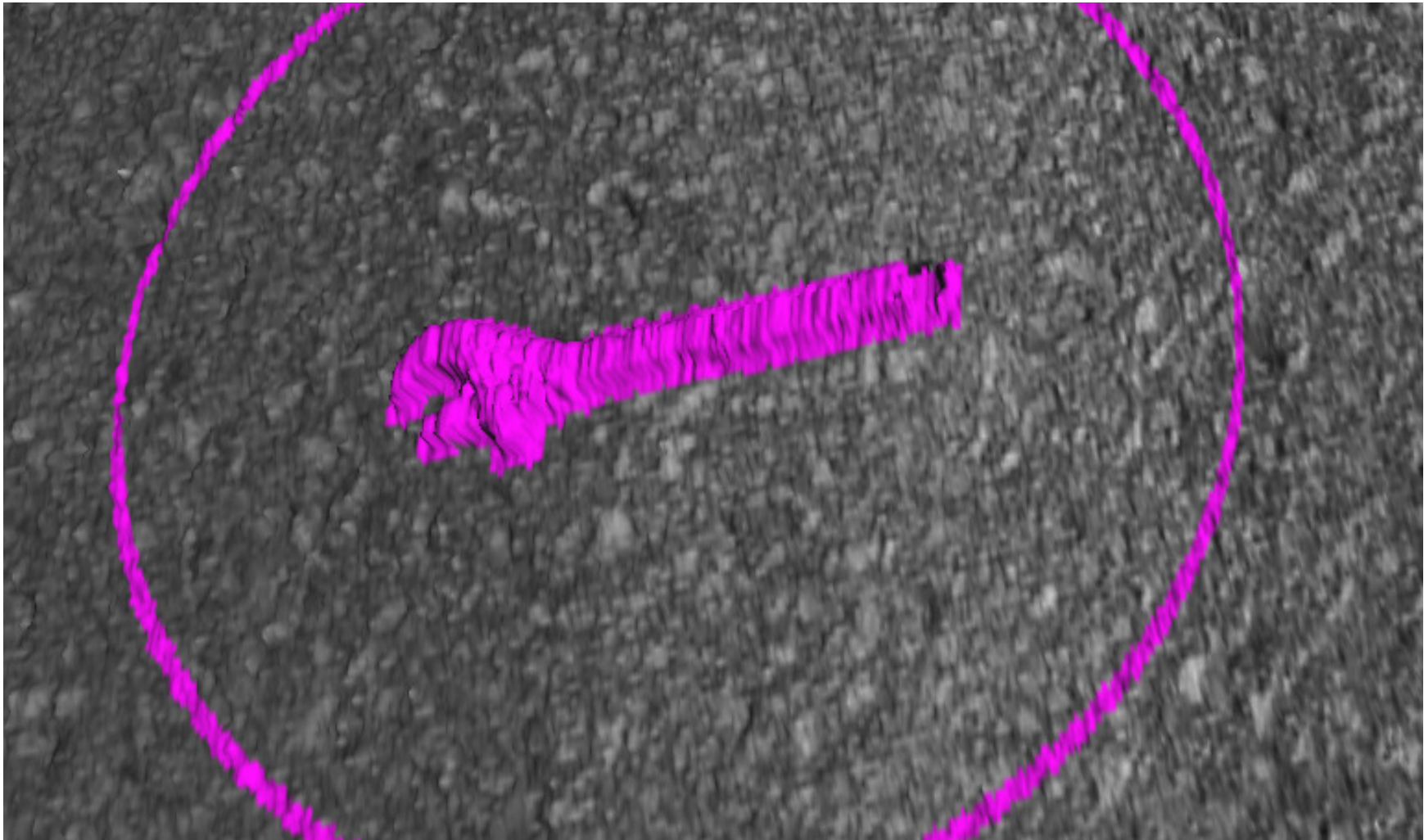








# **FOD Algorithm Detects FOD**



# Photo Submersed FOD, Singapore

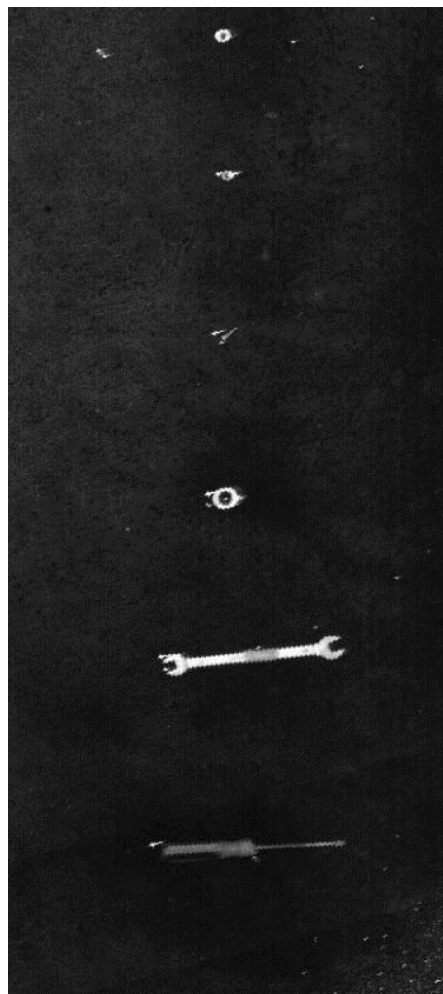


# Photo Submersed FOD, Singapore



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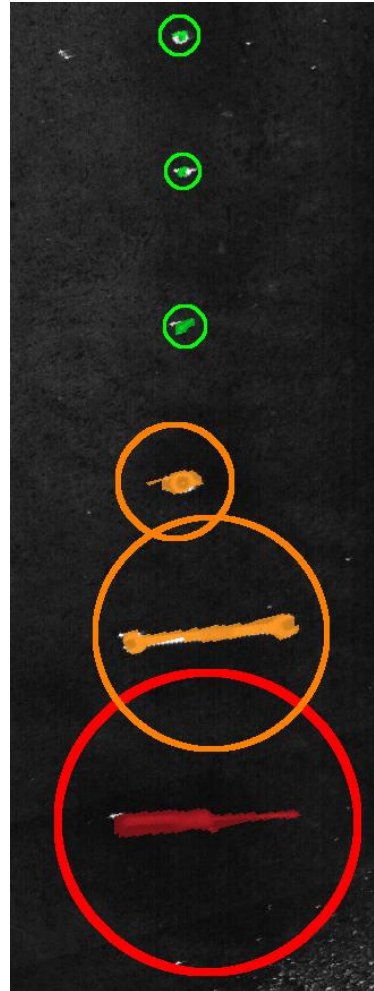
# LFOD Intensity Image of Submersed FOD



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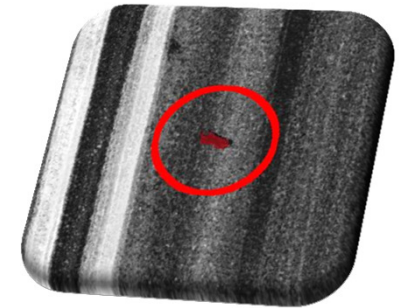
# Automatic FOD Detection of Submersed FOD



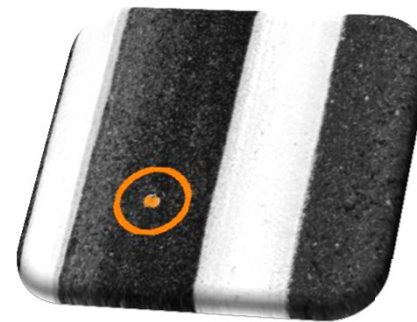
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# Ability to Group FOD According to Size

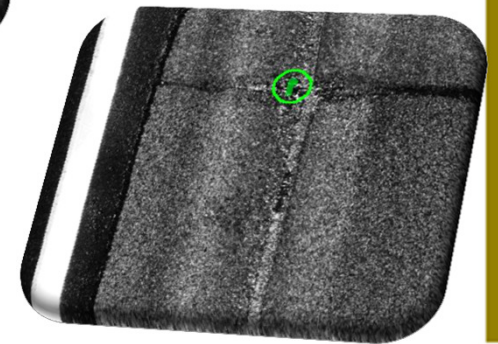
- With greater ability to detect FOD comes the need to reconsider how to react
- Some FOD you will want to stop and immediately collect
- Some FOD you will record details for in order to subsequently deploy sweepers to remove



High



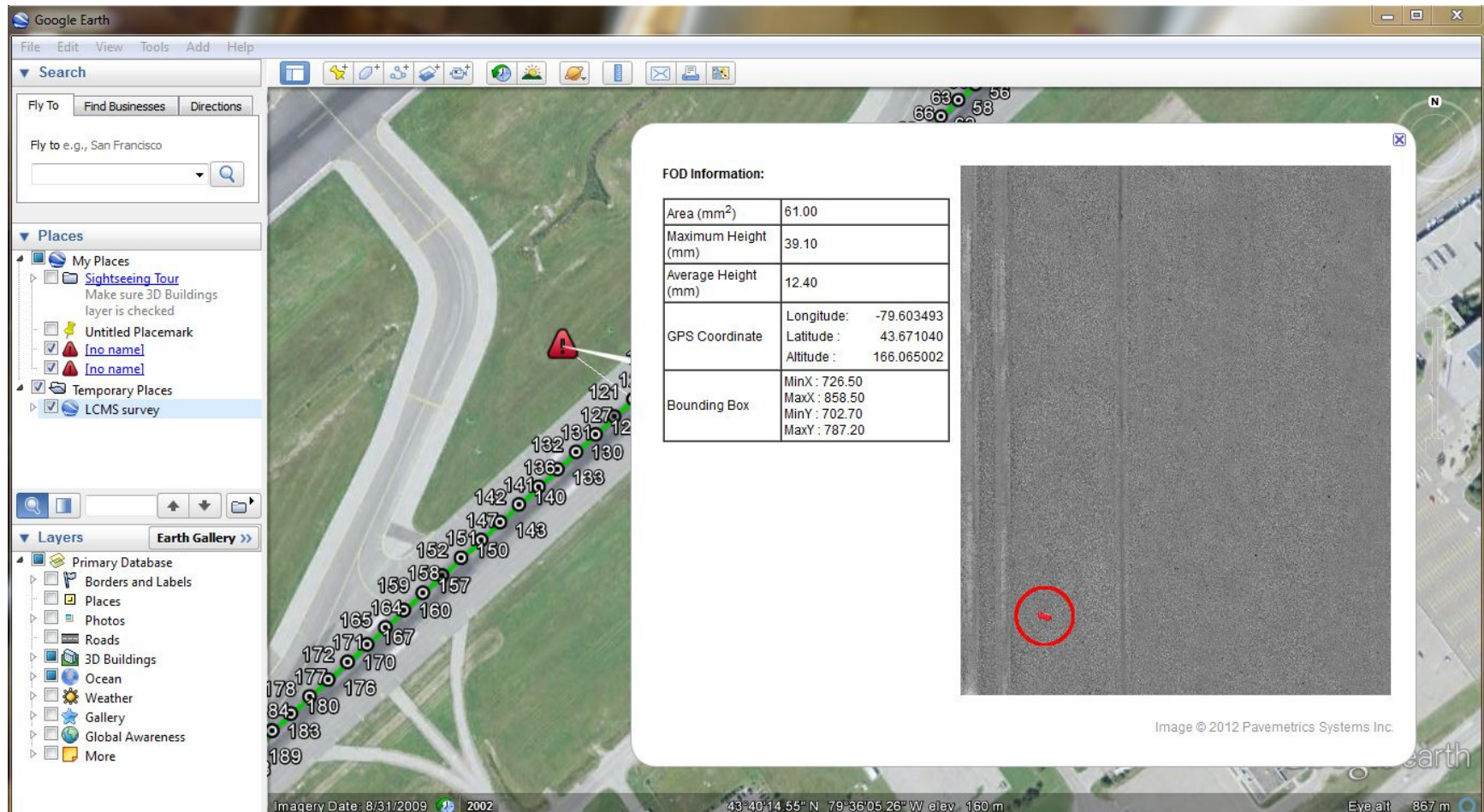
Moderate



Low

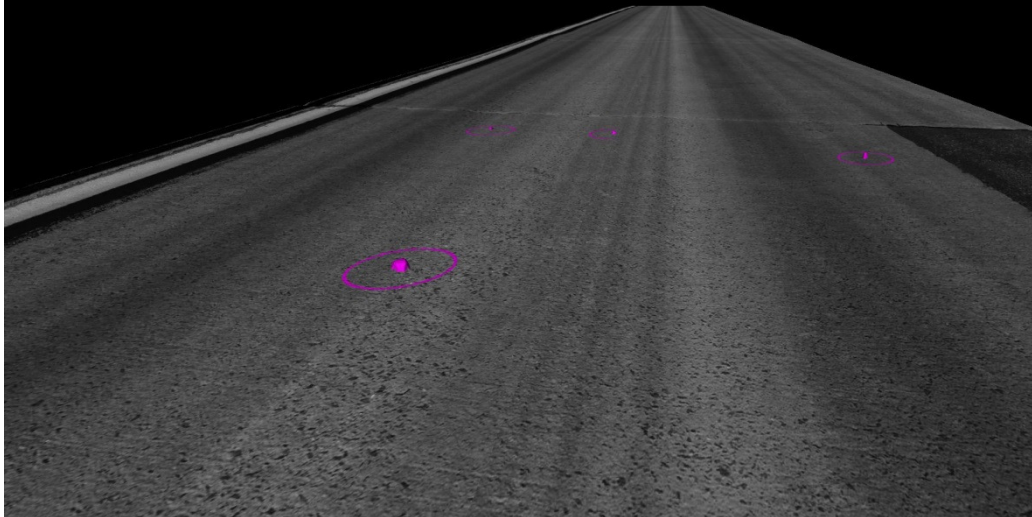


# Detected FOD With Range Image

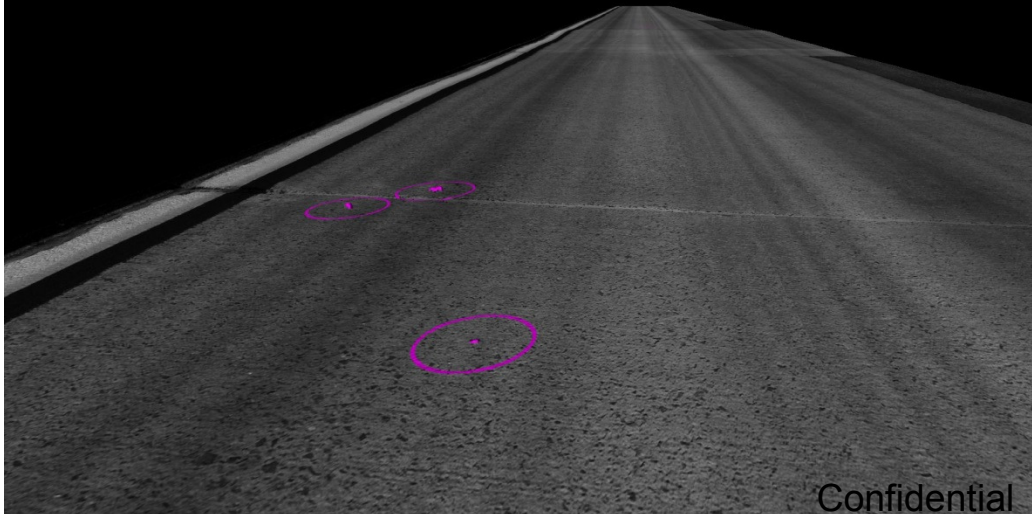


# Detected FOD – Mirabel Data

Mirabel data collected with the LFOD

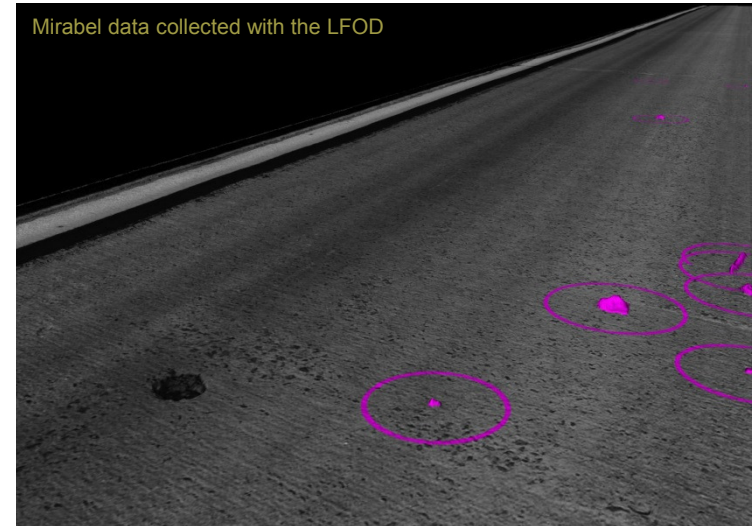


Mirabel data collected with the LFOD



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Mirabel data collected with the LFOD





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**Thank you!**

